

# Cloud-free global maps of four essential vegetation traits retrieved with Gaussian Processes from S3-OLCI catalogue

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# **FLEX - Sentinel 3 tandem mission**



- Goal: Measure Solar Induced Chlorophyll fluorescence and to quantify photosynthetic activity
- Currently NO sensors in orbit specified for capturing SIF
- ESA Earth Explorer 8 Fluorescent Explorer (FLEX) will measure Solar Induced Fluorescence (SIF) at 300m res.
- To be launched in 2025
- Will fly in tandem with Sentinel-3 and benefit from the synergy of OLCI and SLSTR

Our aim: To prepare the workflow and processing chains for future SIF data







To retrieve **temporally reconstructed global maps** of:

- leaf chlorophyll content (LCC)
- leaf area index (LAI)
- fraction of absorbed photosynthetically active radiation (FAPAR)
- fractional vegetation cover (FVC)

To utilize S3 OLCI Top Of Atmosphere (TOA) data and hybrid models trained with: Gaussian Process Regression (GPR) To implement these models into Cloud computing (Google Earth Engine GEE) Reconstruct with Whittaker's smoother to achieve cloud free data (WS)

**Correlate** against Copernicus & MODIS products









#### **Method of Retrieval**



- 1. Retrieval started with canopy state simulation using the **SCOPE** v.1.7
- 2. SCOPE **Top Of Canopy** (TOC) were upscaled to  $\rightarrow$ **TOA** using **6SV** RTM<sup>[1]</sup>
- 3. Coupling process realized by: Atmospheric Lookup table Generator (ALG)<sup>[2]</sup> and Automated Radiative Transfer Models Operator (ARTMO)<sup>[3]</sup>
- 4. GPR models were trained using TOA radiances and mapped in GEE
- 5. Spatiotemporally continuous dataset were obtained by using the WS

LCC LAI FAPAR FVC S3-TOA-GPR-1.0-WS models

[1]: Vermote et al. (1997)[2]: Vicent et al. (2020)[3]: Verrelst et al. (2012)



#### **Processing S3-TOA-GPR-1.0-WS models**

Whittaker's smoother for temporal reconstruction:

- Penalty weight  $(\lambda) = 100$ , quickly adjustable
- Gaps around low latitudes and polar regions
- Algorithm directly implemented into GEE
- λ can be adjusted quickly



 $(\mathbf{I} + \lambda \mathbf{D'D})\mathbf{z} = \mathbf{y}$ 

Whittaker's governing linear system of





#### **Global maps**



Temporally reconstructed gap-free maps. 10th July 2019 (5km resolution)



SCERIN - Brno 26-29th June 2023

# **Regional maps at 300m resolution**



- 300m (nominal OLCI) resolution results higher memory usage
- Can be used for regional analysis
- 5km is perfectly fine for global applications



10th July 2019 (300 m resolution)

#### **Uncertainty maps**



The Bayesian GPR algorithm also provides associated uncertainties ( $\sigma$ ) Each  $\sigma$  relates to the absolute value of the estimate



# Intra-annual comparison



Per-pixel intra-annual comparison for 2019 of the 4 products:

- Against Copernicus (CGLS) and MODIS reference products
- High consistency over 30-60° latitudes



- Lower consistency over latitudes lower than 20°
- Pronounced yearly phenology yielded superior GPR retrievals



### **Environmental causality**





- Important remark for models:
  - Soil moisture and precipitation
- Shrublands are much more "sensitive" to precipitation and soil moisture increments
- Interesting vegetation dynamics highly caused by soil moisture





# Validation



- Against VALERI ground measurements
- FAPAR and FVC best performer followed by LAI
- Overestimation of LAI (grassland and crops)

- FAPAR class samples more "compactly" distributed
- FVC underestimations over pine forests Validation by Reyes-Muñoz, et al 2022



# Land cover specific analysis



#### Variables correlated on over

- Evergreen broadleaf (EB)
- Deciduous broadleaf (DB)
- Agricultural (rice and wheat) (AG)
- and Sparse land covers (SP)

Highest correlations, all over DB, yielded by:

- 1. FVC R=0.98 vs. CGLS
- 2. LAI R=0.95 vs. CGLS
- 3. LAI R=0.95 vs. MODIS



# **Advantages of Cloud computing**



Retrieval can be customized by the user

Processes run on servers, the retrieval can be run on any user's device

Retrieved maps can be downloaded as ".tiffs" and used for further processing

#### Retrieval widely customisable by freely adjusting:

- Region of interest
- Temporal composites
- Whittaker's lambda can be adjusted freely
- Dates of retrieval: 2016 onwards (S3's launch)
- Spatial resolution







- Cloud based GPR models: can be easily implemented operationally
- Methodology spatially and temporally scalable
- General consistency with MODIS and CGLS products
- Validity is correlated to vegetation seasonality
- Further validation will provide more information about consistencies
- Easily implemented by public users

Any questions?

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Link to GitHub repo:

daviddkovacs/Global-EVT-maps