High-Resolution Global Monitoring of Urban Settlements SCERIN–1 Meeting

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Knowledge for Tomorrow

Global Perspective on Human Settlements



- → 180.000 additional urban inhabitants per day
- ✓ Number of megacities from currently 25 to more than 100 within the next 30 years
- China: 30 new cities with >1 million inhabitants in next two decades
- → India: 26 new cities with >1 million inhabitants in next two decades

Planning Times

- For an effective planning it is necessary to reliably know which is the current extent of urban areas;
- In developed countries cadastral data are generally available [however, it might be sometimes difficult to get all the necessary information when regional (or national planning) has to be investigated];
- In developing or under-developed countries often no official records are available and heavy informal settlement regularly occurs! (and the population growth here is 6 times faster).



Planning Times

- In the last decade several EO-based and EO-supported Global Human Settlements Layers (GHSL) have been produced to map human settlements worldwide.

NASA global nighttime lights product derived from imagery of the Visible Infrared Imaging Radiometer Suite (VIIRS)



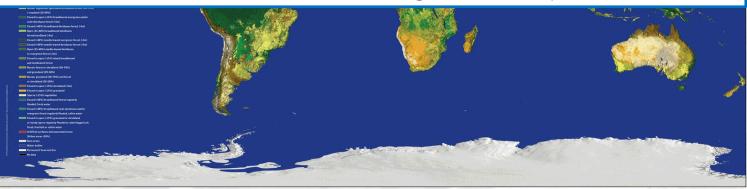
Planning Times

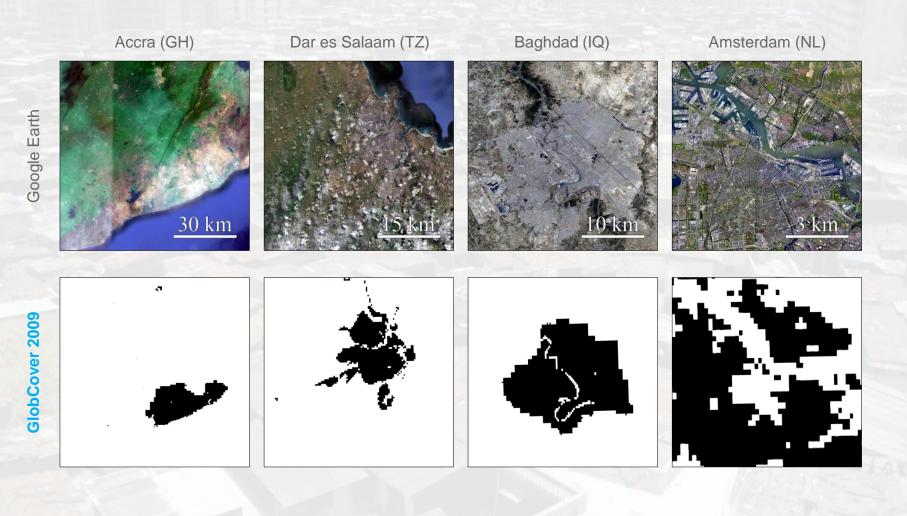
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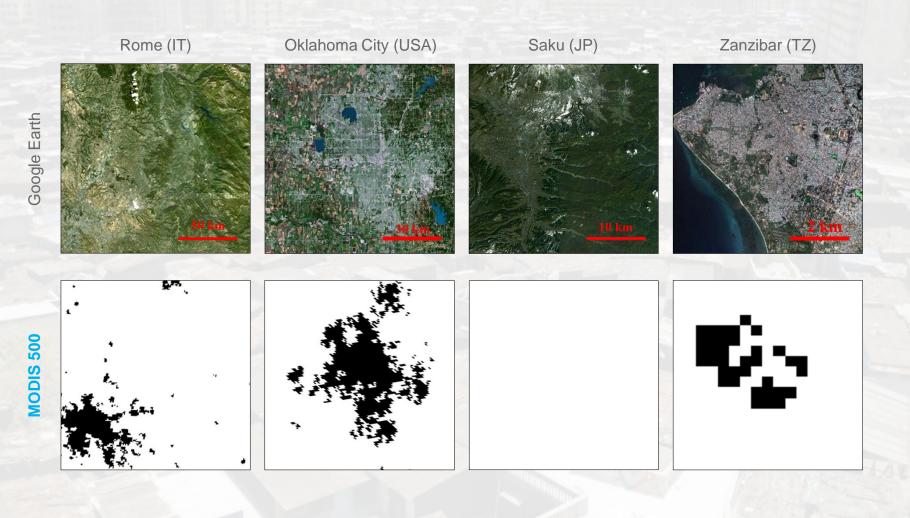
NASA MODIS 500 (493 m spatial resolution) and ESA GlobCover 2009 (309 m spatial resolution)



The limited spatial resolution does **NOT** allow a precise characterization of urban settlements, especially in rural and peri-urban areas (characterized by small and scattered villages and towns)







Prague (CZ)





Google Earth

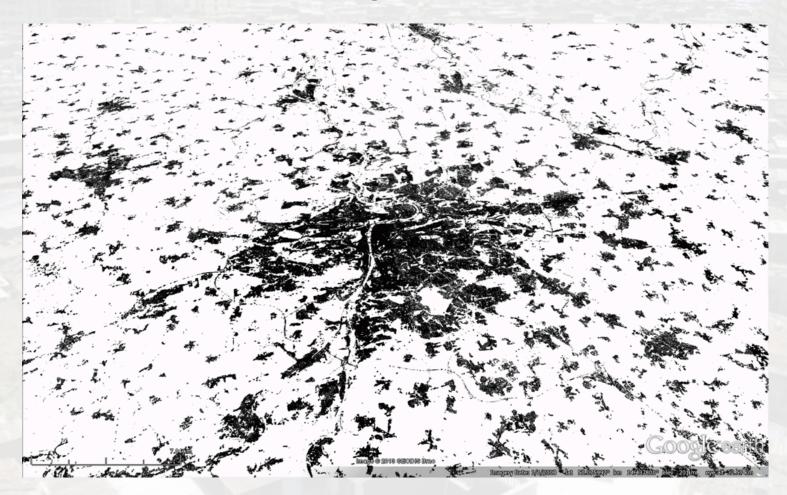
GlobCover 2009



DLR



DLR

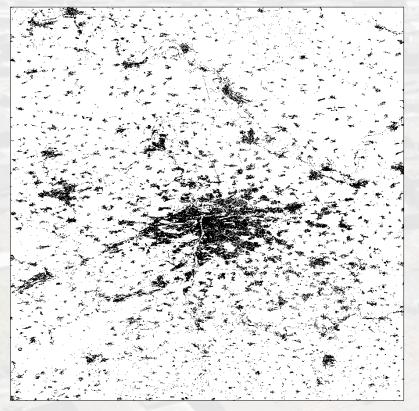


DLR



DLR

Prague (CZ)

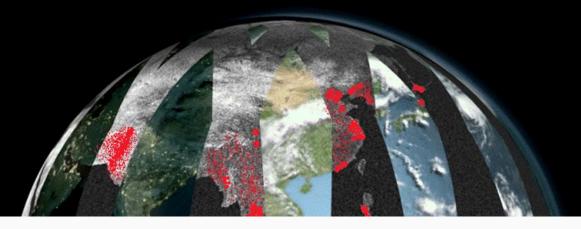






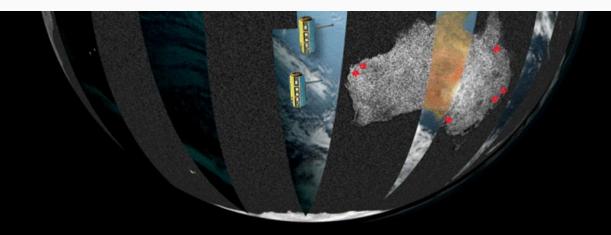
GlobCover 2009

Global Urban Footprint 2011 / 2012

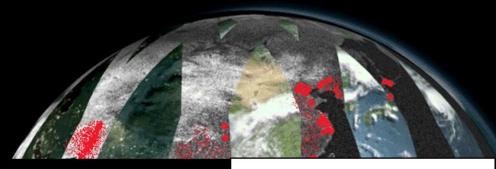


Global Urban Footprint initiative

- World-wide inventory of human settlements using data of TanDEM-X mission;
- Generation of binary settlement masks at VHR;
- Basis for analysis of urban and rural settlement patterns.



Global Urban Footprint 2011 / 2012

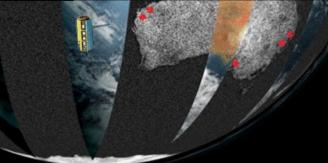




TanDEM-X mission:

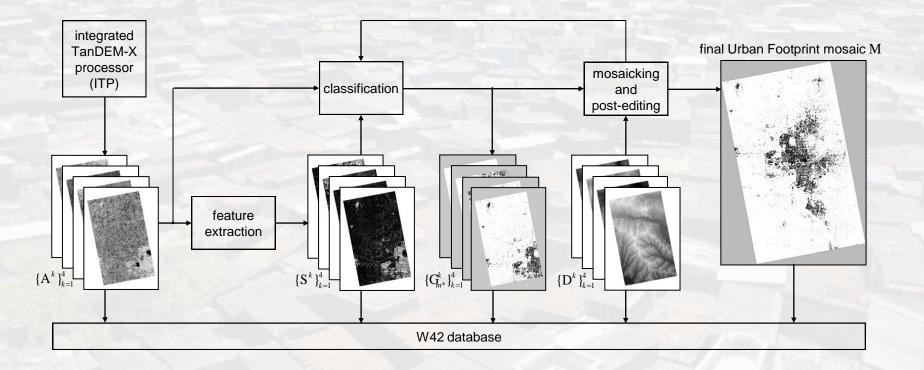
- two radar satellites (TSX, TDX)
- global digital elevation model
- image data: ~3 m
- two global coverages (2011, 2012)
- DEM standard products: ~ 12 m

Finalization of Global Urban Footprint layer planned for 2013



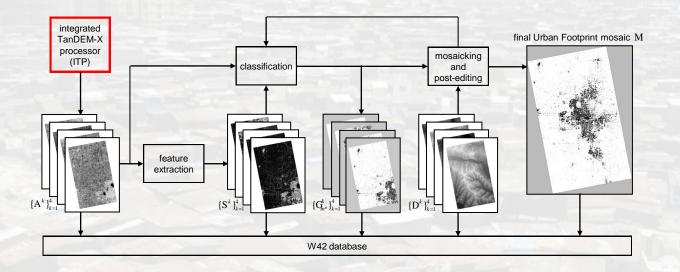
Urban Footprint Processor

- The novel fully-automatic processing chain for the production of the GUF is referred to as **Urban Footprint Processor** (UFP):





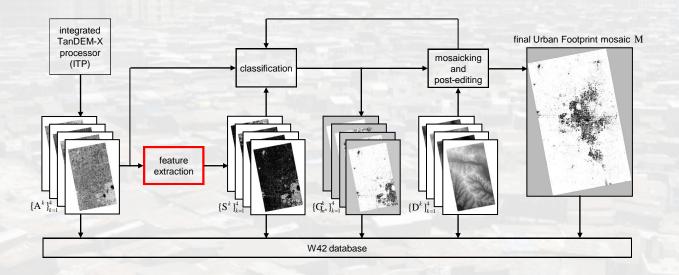
Urban Footprint Processor – Input



- Total number of more than ~180,000 radar images composing one global TDM coverage (each one with average size of ~50,000 x 45,000 pixels adding up to a final data volume of ~300 TB);
- SSC images are rescaled to a spatial resolution of about ~0.4 arc sec (~12 m, i.e., the highest resolution in which the global DEM produced in the context of the TDM will be made available).



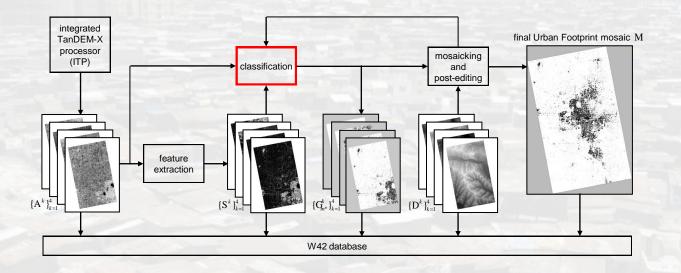
Urban Footprint Processor – Feature Extraction



- The objective of the feature extraction is to derive **effective texture information** for highlighting regions characterized by highly structured and heterogeneous built-up areas;
- To this aim we extract the so-called "speckle divergence" feature Σ, which accounts for the specific characteristics of SAR data that exhibit strong scattering due to double bounce effects in urban areas;



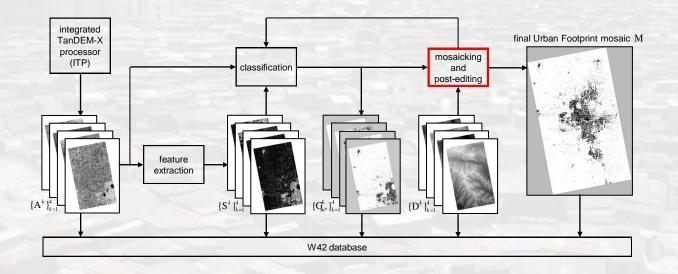
Urban Footprint Processor – Classification



- The aim of the classification stage is to automatically derive a binary settlement layer (built-up, non-built-up) for the investigated scene once provided as input with the backscattering amplitude A and the corresponding speckle divergence Σ;
- To this aim we developed a **novel unsupervised and fully automatic technique** which proved extremely **robust** and **effective**.



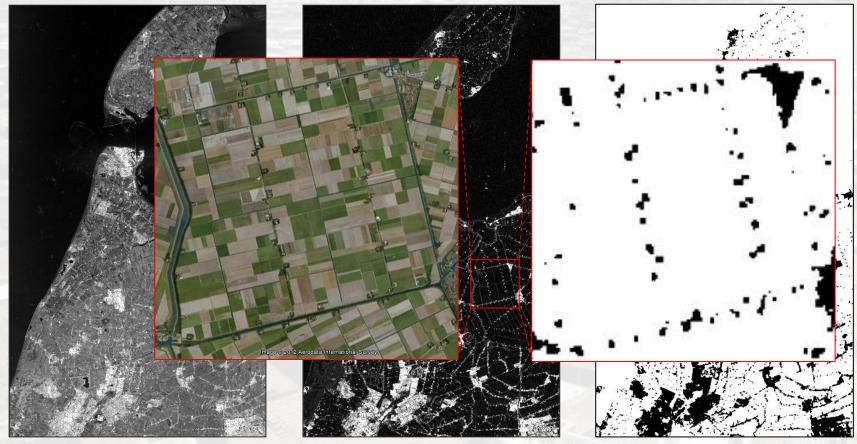
Urban Footprint Processor – Mosaicking and Post-editing



- To overcome overestimation due to topography effects in hilly and mountainous areas, we implemented a dedicated mask derived from the analysis of the ASTER Global DEM.
- In particular, we mark as non-urban all those pixels whose slope (intended as the maximum rate of height change between each pixel and its closest eight neighbors) is higher than 20 degrees in the neighborhood of a local peak.



Urban Footprint Processor – Classification

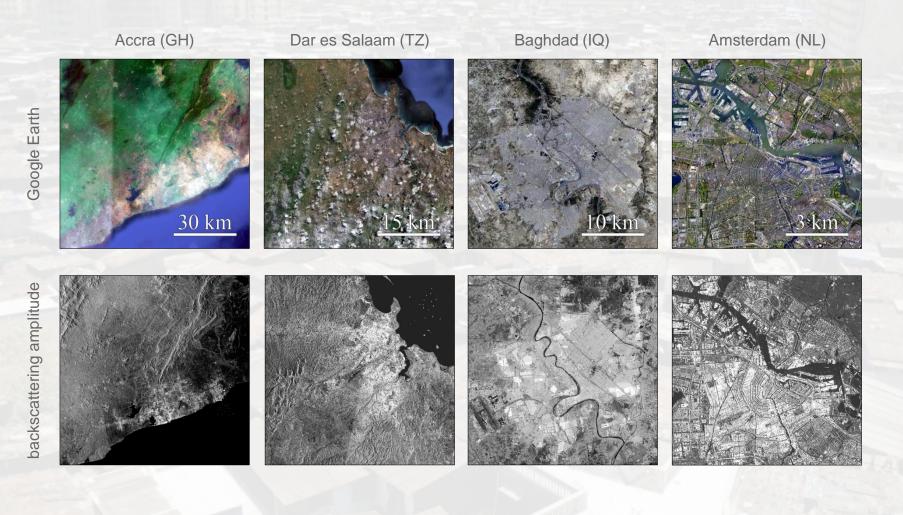


backscattering amplitude

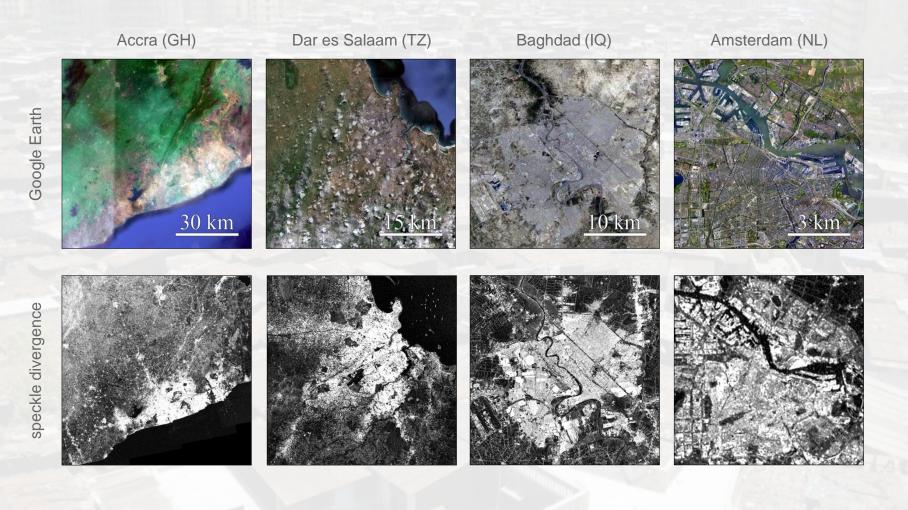
extracted speckle divergence

Global Urban Footprint

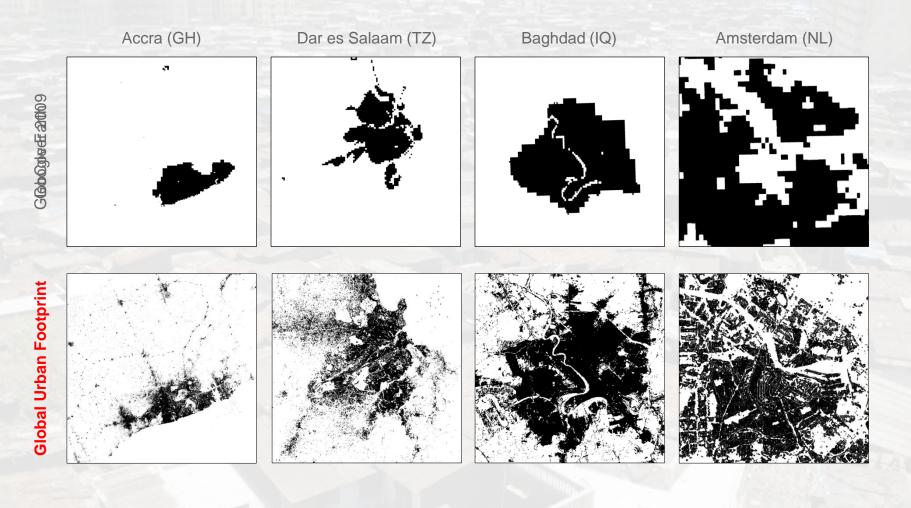
Global Urban Footprint vs. GlobCover 2009



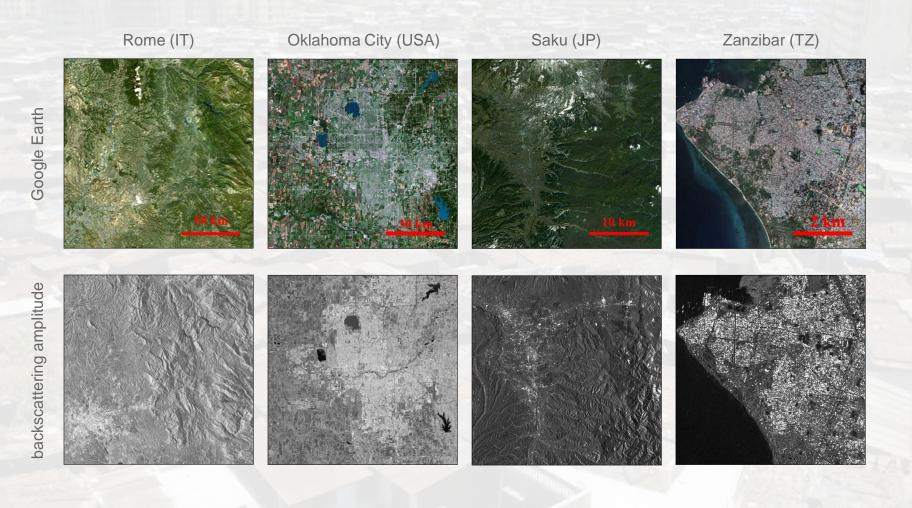
Global Urban Footprint vs. GlobCover 2009



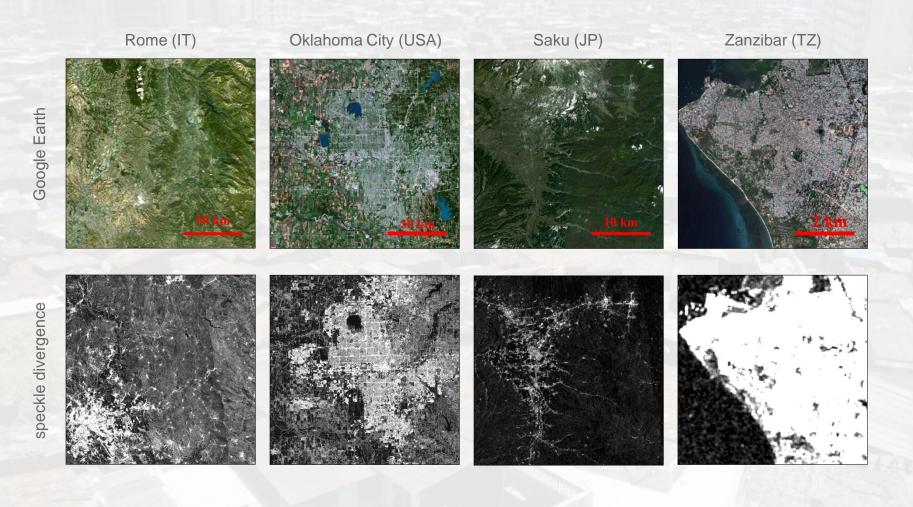
Global Urban Footprint vs. GlobCover 2009



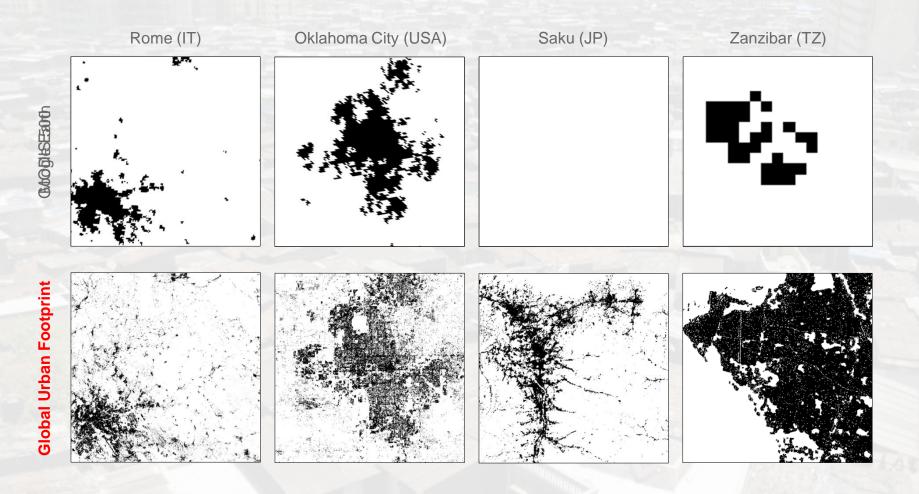
Global Urban Footprint vs. MODIS 500



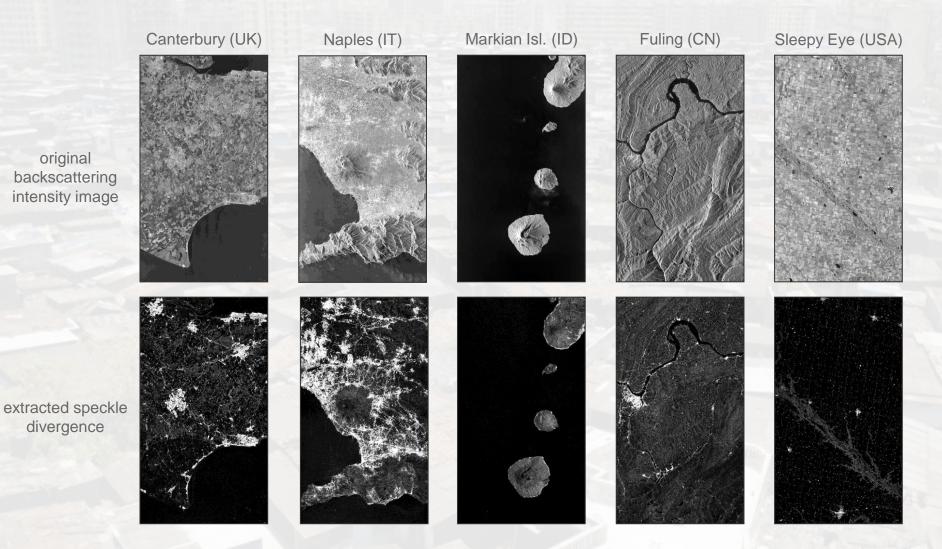
Global Urban Footprint vs. MODIS 500



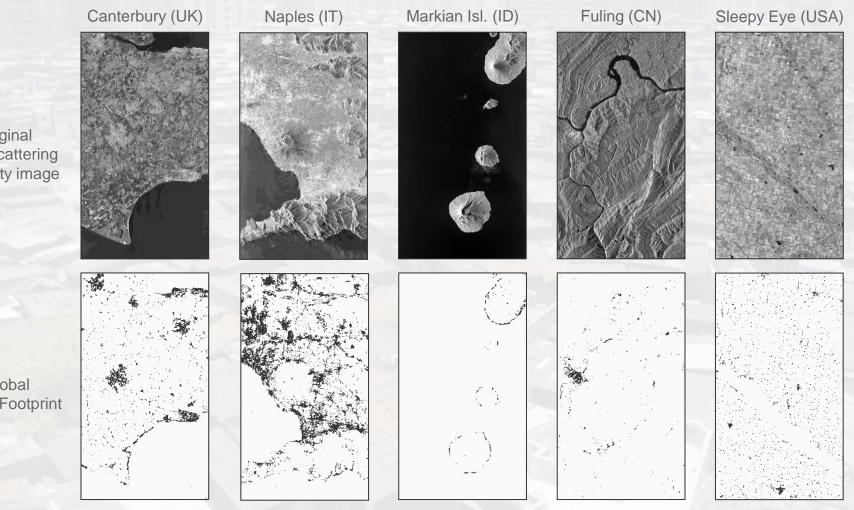
Global Urban Footprint vs. MODIS 500



Global Urban Footprint – Key Examples



Global Urban Footprint – Key Examples



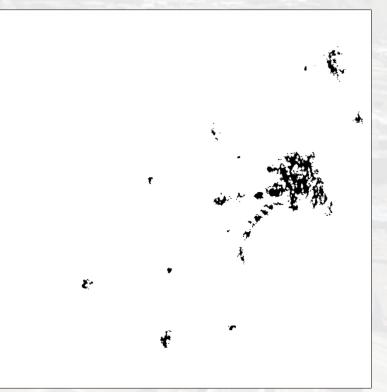
original backscattering intensity image

Global Urban Footprint



Global Urban Footprint – Zealand (Denmark)





Google Earth

GlobCover 2009

Global Urban Footprint – Zealand (Denmark)





Global Urban Footprint

GIUKKAR/ME2609

Global Urban Footprint – New Delhi (India)



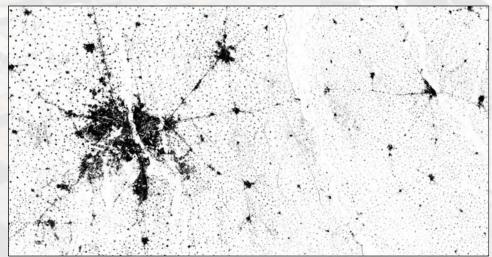
Google Earth

New Delhi Area: 88 images (~90,000 km²)

original backscattering amplitude

extracted speckle divergence

Global Urban Footprint



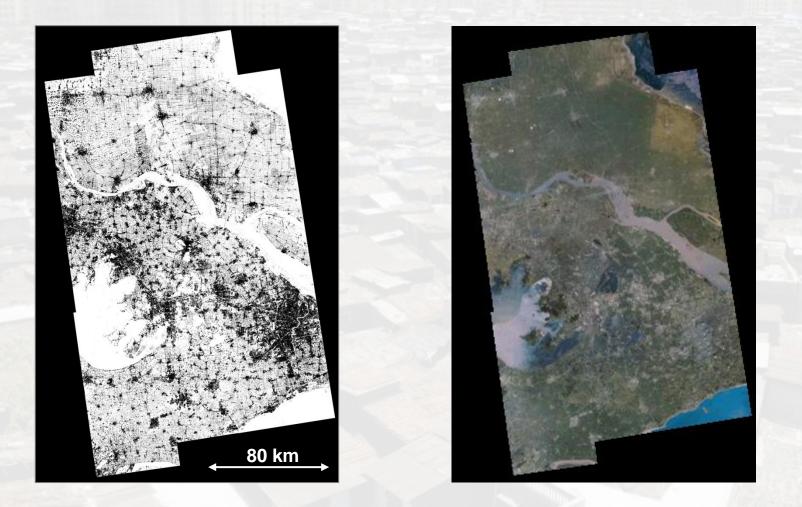


Global Urban Footprint – Japan

Japan: ~800 images

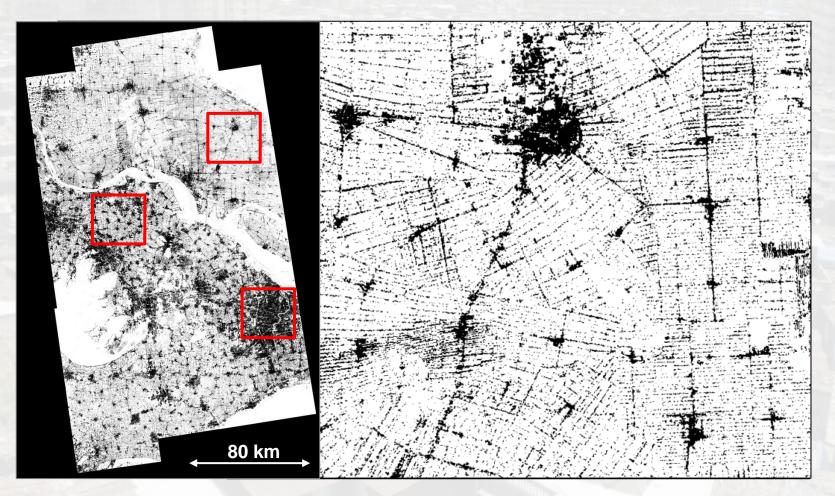
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Global Urban Footprint – Shanghai (China)



DLF

Global Urban Footprint – Shanghai (China)

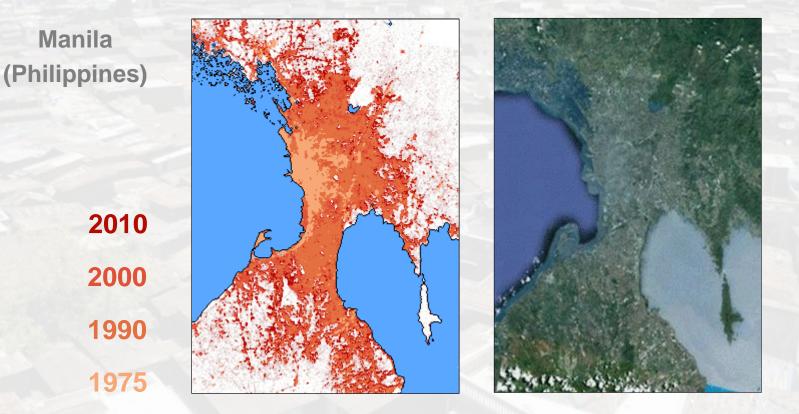


Urban Footprint

DLR

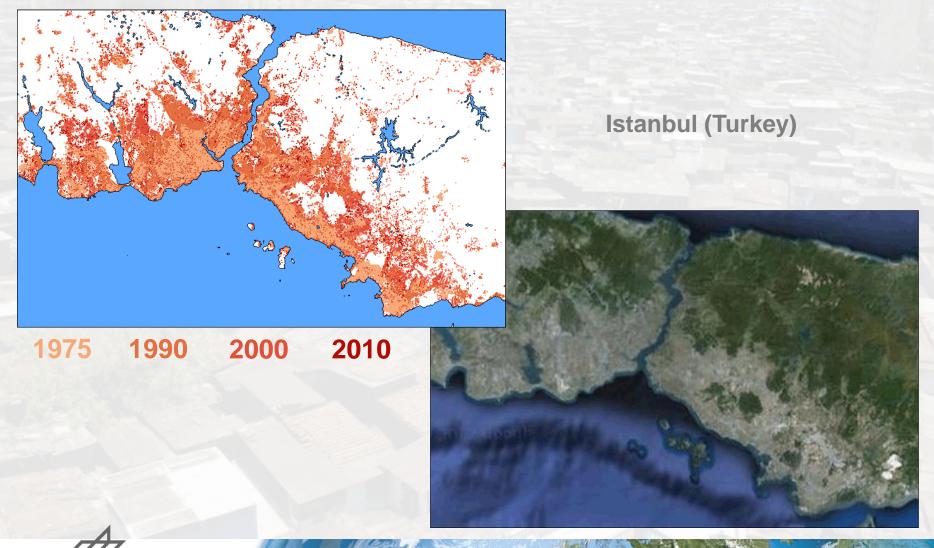
What's next? – Global Urban Growth

Urban spatio-temporal development based on historical optical (Landsat MSS, TM and ETM+) and SAR (ERS, ASAR) data + Global Urban Footprint.





What's next? – Global Urban Growth

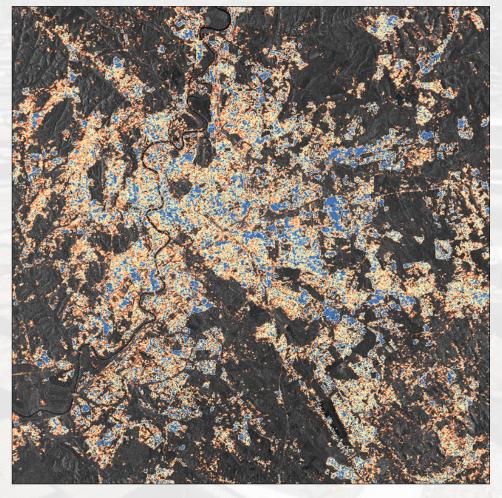


DLR

What's next? – Urban Structural Analysis

Estimation of **building density** (concentration of buildings in a given area)

→ key parameter for classification of urban structure types and derivation of building usage



Estimated building density (50x50 m²)

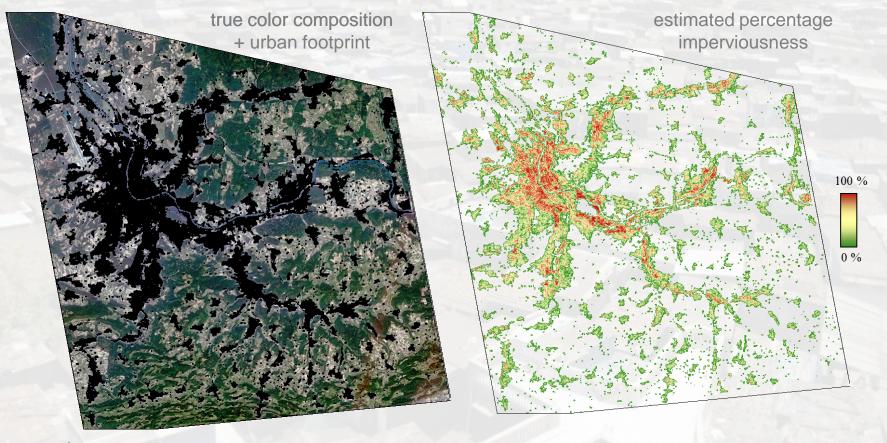


>80%

What's next? – Percentage Imperviousness

Percentage imperviousness (i.e. percentage of artificial structures covered by impenetrable material) estimated by means of HR optical data (e.g., SPOT, RapidEye) and empirical modelling

Basel (Switzerland) - RapidEye image



What's next? – Building Structure Characterization



Estimated Building Structure (GUF postprocessing)



True Building Structure

What's next? – Building Structure Characterization



Estimated Building Structure (GUF postprocessing)



True Building Structure

Conclusions

- The presented GUF has already been produced for thousands of images worldwide and preliminary validation results assess its great potential to:
 - support the research into global urbanization patterns;
 - investigate spatiotemporal aspects of (peri-) urbanization;
 - support transdisciplinary and structural analyses.
- Extensive quantitative validation of the GUF based on in situ ground-truth information is ongoing;
- The production of the first GUF layer from the first TDM data coverage is envisaged for 2014 (a public domain version will be made available at ~50-75 m);
- For research purposes it will be possible to access the full-resolution product at 12 m resolution;
- A dedicated website will be online soon.



... Thanks a lot for your attention! ...

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